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Proyecto CLIMA

## Behavioral Decision Theory:

# How Judgments and Decisions are Made Under Uncertainty



## Lesson 2

### Normative and Prescriptive Decision Models

# Types of Models

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## □ Normative

- A standard that defines “best” way of achieving some goal
  - Goals include maximization, optimization, consistency across situations and contexts

## □ Descriptive

- Describe how people normally think and decide
- Often expressed in terms of heuristics/simple rules
- Can also describe regularities of behavior mathematically

## □ Prescriptive

- Prescribe how we “ought” to think or act
- Often derive from normative models, but can also involve heuristics/shortcuts
- Successful prescriptive models will also incorporate lessons from descriptive models

# Decision Making as Constrained Optimization

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- Specification of Objective Function
  - Objective function specifies ***decision rule***
  
- Identification of Constraints
  - Physical (engineering) models have physical constraints
  - Normative decision models have logic and consistency constraints (axioms)
  - Descriptive decision models have cognitive and affective constraints

# Example of a physical constraint optimization problem

- Maximize the rectangular area that can be enclosed by 24 feet of fencing material

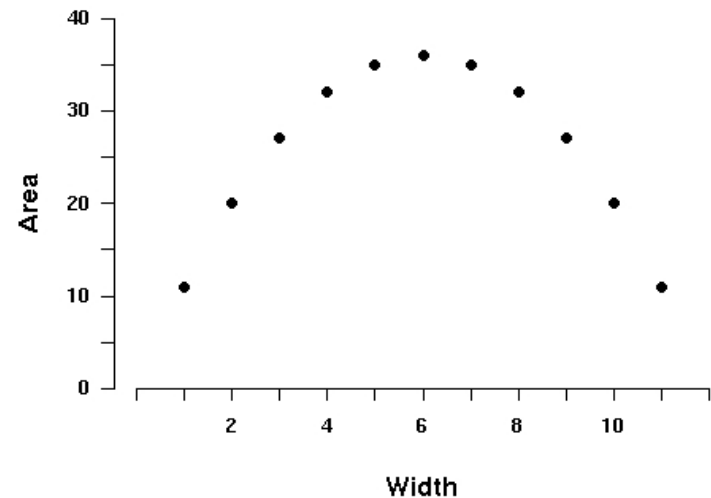
area of rectangles with fixed perimeter

$$\text{Perimeter}=24$$

$$\text{Area} = L \times W$$

$$L + W = 12$$

$$\text{Area} = (12-W)W$$



# “A Decision Theorist Reads the Newspaper”

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- New York Times, Sept. 3, 2006 story on air traffic controller staffing decisions made by Federal Aviation Agency and airports
  - Conflicting goals
    - Maximize public safety
    - Minimize expenses
  - Optimization involves specification of a tradeoff factor
    - Relative importance of safety vs. costs
      - Adjustments of relative importance weights with feedback
        - e.g., accidents that involve loss of lives, like the crash of a Boeing737 of the Brazilian airline Gol Transportes Aereos, on September 29, 2006, on route from Manaus to Brasilia, causing 154 fatalities, no survivors (after mid-air collision with business jet which landed safely with some damage to the aircraft)

# Where do decision rules come from?

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## □ They are *learned*

- by experience (induction)
  - “learning by getting hurt”
- by observing others
  - “learning by watching”
- by explicit instruction
  - “learning by being told”

## □ They are *deduced*

- using logic and mathematics

# Historical Example: The St. Petersburg Paradox

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## □ Game:

- You get to toss a fair coin for as many times as you need to score a “head” (H)
- $n$  is the toss on which the first H appears:  $1 \leq n \leq \infty$

## □ Payoff:

- You get  $\$2^n$ 
  - If you score H on toss 1, you get \$2
  - If you score H on toss 2, you get \$4
  - If you score H on toss 3, you get \$8
  - If you score H on toss 4, you get \$16, etc.

## □ Question:

- How much are you willing to pay me in order to play this game for one round?
- How do you decide???

## ***Expected Value* of one Round of the Game**

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□ How much do you think you can expect to win in one round of this game?

□  $EV(X) = \sum_i (x_i p(x_i)) = ?$

□ Is EV a good decision rule for how much to pay for this game?

■ No!

■ Instead, Bernoulli (1834) suggested that we compute expected utility of outcomes, where utility is decreasing over amount

□ Logarithmic function



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## □ Expected Utility of Game

- Daniel Bernoulli (1739)
  - Utility of wealth is not linear, but logarithmic
  - $EU(X) = \sum_i \{u(x_i) p(x_i)\}$

## □ Other decision rules

- **Minimum return (pessimist) rule:**
  - pay no more than you can expect to get back in the worst case
- **Expectation heuristic (Treisman, 1986):**
  - figure on what trial you can expect to get the first H and pay no more than you will get on that trial

# *Examples where EV is a good decision rule*

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## □ Pricing insurance premiums

- Actuaries are experts at getting the relevant information that goes into calculating the expected value of a particular policy

## □ Testing whether slot machines follow state laws about required payout

# Expected Utility Theory

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- Generally considered best normative “objective function” since its axiomatization by von Neumann & Morgenstern (1947)
  - Rationality axioms seem reasonable and desirable
  - EU maximization follows (deductively) from axioms and does not depend on any “long-run” argument

# Expected-Utility Axioms

(Von Neumann & Morgenstern, 1947)

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- Connectedness

$x \succsim y$  or  $y \succsim x$

- Transitivity

If  $x \succsim y$  and  $y \succsim z$ , then  $x \succsim z$

- Substitution Axiom or Sure-thing principle

If  $x \succsim y$ , then  $(x, p, z) \succsim (y, p, z)$  for all  $p$  and  $z$

- If you “buy into” all axioms, then you will choose  $X$  over  $Y$

- if and only if  $EU(X) > EU(Y)$ ,

where  $EU(X) = \sum_i \{u(x_i) p(x_i)\}$

and  $EU(Y) = \sum_i \{u(y_i) p(y_i)\}$

# Discounted Utility Model

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- For outcomes that occur not now, but later in time, utility of the outcome is discounted by a factor  $d$ 
  - Discount factor  $d$  indicates how much a dollar received now would be worth if it is received in a year
    - $d=1$  means that there is no discounting: one dollar in a year is valued the same now as a dollar now
    - $d=.50$  means that there is some discounting: one dollar in a year is equivalent to receiving 50 cents now

# Decision Analysis as a Way to Implement EU Maximization

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## □ Structuring of the decision

### □ Decision tree

- Action nodes
- Chance nodes
  - Probabilities need to be assessed
  - Utilities of component dimensions and tradeoff coefficients need to be assessed

## □ How to get those values?

### □ Direct ways

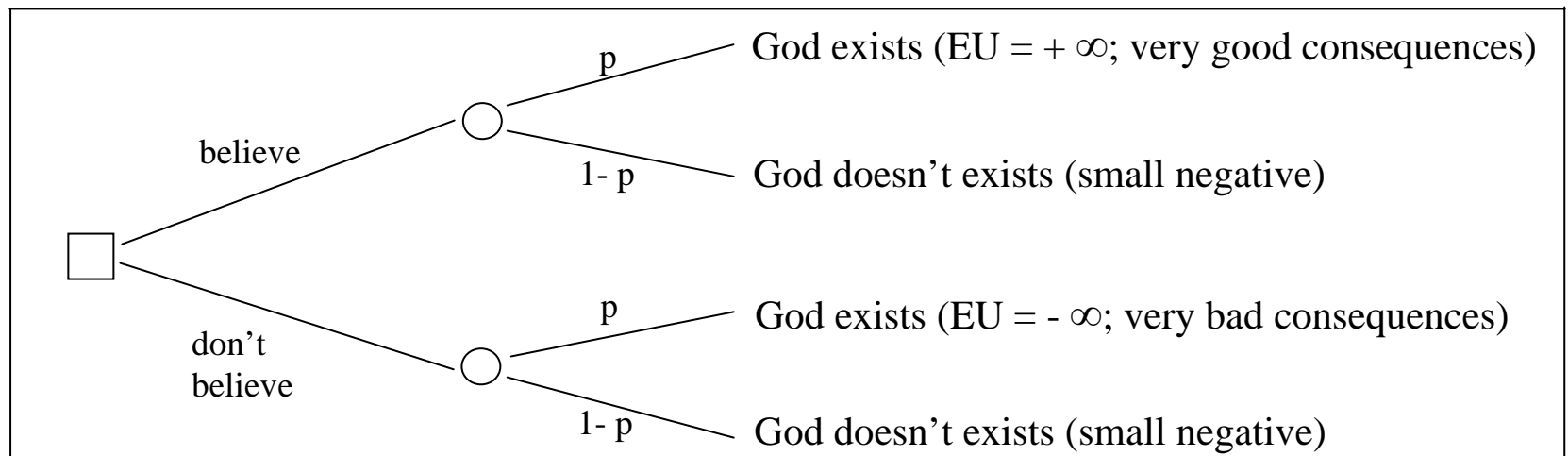
- Ask decision maker or experts directly
  - “how likely is given event?” (absolute judgment)
  - “how useful/valuable is given outcome?” (relative judgment)

### □ Indirect ways

- From logic or past experience
- Ask decision maker about hypothetical decisions (“standard gambles”)
  - Work backwards from choice to determine underlying utilities

## States of nature

	God exists	God does not exist	
	$p$	$1 - p$	
Action 1: "Believe"	Utility = $+\infty$ (infinitely positive)	Utility = $-e$ (very small negative)	EU("believe") = $\infty$
Action 2: "Don't believe"	Utility = $-\infty$ (infinitely negative)	Utility = $+e$ (very small positive)	EU("don't believe") = $-\infty$



Therefore, according to Pascal, believing in God is a dominating alternative if you want to maximize expected utility!

# What do normative/prescriptive models provide?

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- Consistency in choices
- Structure for decision making process
- Transparency of reasons for choice
- Justifiability
- “Education” of other choice processes



# Multi-Attribute Utility Theory (MAUT)

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- ❑ Model of riskless choice
  - ❑ Choice of consumer products, restaurants, etc.
  
- ❑ Need to specify
  - ❑ Dimensions of choice alternatives that enter into decision
  - ❑ Value of each alternative on those dimensions
  - ❑ Importance weights of dimensions given ranges (acceptable tradeoff)
  
- ❑ Tradeoffs
  - ❑ Willingness to interchange  $x$  units of Dimension 1 for  $y$  units of Dimension 2
  - ❑ Computer programs can help you with utility assessment and tradeoff assessment

# Renting Land Example

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- $MAU(\text{Rental}) = b_w u(\text{Price/ht})$   
+  $b_s u(\text{Payment Option}) + b_l u(\text{Soil Quality})$ 
  - $u(\cdot)$  are the utility functions on individual rental attributes
  - $b$ 's are the importance weights of attributes
  
- Possible Interactions

# Utility Elicitation Method

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- “standard gamble” methods
  - using certainty equivalents
    - Compare lottery against sure thing of equal EV and adjust sure thing value until two options equally valued
  - use probability equivalents
    - Compare two lotteries and adjust one probability level until two options equally valued
  - why would elicitation method make a difference?
    - “Stay tuned” for prospect theory and certainty effect